

*Smart strain sensor*

# epsimetal<sup>®</sup>



## USER MANUAL

The technical data are given in this handbook on a purely indicative basis and are not contractual. They can be modified at any moment according to the technical requirements.

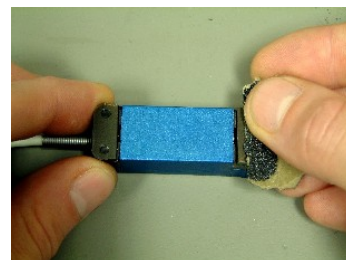
<b>BONDING PROCEDURE.....</b>	<b>3</b>
<b>I. PREPARING THE MOUNTING SURFACES : .....</b>	<b>3</b>
<b>II. SENSOR BONDING: .....</b>	<b>3</b>
1. Cyanoacrylat glue:.....	3
2. Epoxy Bi-Components Glue: .....	4
<b>III. REMOVING THE SENSOR: .....</b>	<b>4</b>
<b>RE-USING THE SENSOR .....</b>	<b>5</b>
<b>I.MOUNTING THE PLATES ON A SENSOR AND RE-USING IT: .....</b>	<b>5</b>
<b>II. RE-USING A SENSOR ON BONDED PLATES: .....</b>	<b>5</b>
<b>USING DIGITAL ADJUSTMENT: .....</b>	<b>6</b>
1. Available functions : .....	6
3. Connecting the interface box.....	7
2. using parameter adjustment.....	7
<b>DATA SHEET: HIGH LEVEL OUTPUT SENSORS.....</b>	<b>10</b>
<b>I. TECHNICAL DATA : .....</b>	<b>10</b>
1. input :.....	10
2. output (standard version) : .....	10
3. operational conditions : .....	10
<b>II. WIRING (VOLTAGE OUTPUT) : .....</b>	<b>11</b>
<b>III. WIRING (CURRENT LOOP) : .....</b>	<b>12</b>
<b>DATA SHEET : MV OUTPUT SENSORS .....</b>	<b>12</b>
<b>I. TECHNICAL DATA : .....</b>	<b>12</b>
1. input :.....	12
2. output : .....	13
<b>II. WIRING : .....</b>	<b>13</b>
<b>SIZE DRAWING .....</b>	<b>13</b>

All accessories shown in this notice are available by SCAIME. Technical specifications : "FT-Accessoires-Epsi" et FT-Epsimetal".

# BONDING PROCEDURE

## I. PREPARING THE MOUNTING SURFACES :

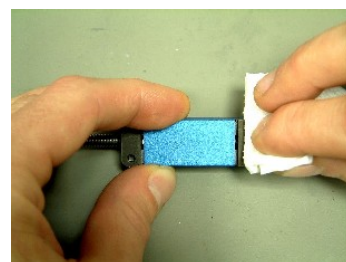
- Make sure that the surface on which the sensor will be bonded (referred to as "mounting surface") is flat. Remove all burrs and unevenness (paint drops, soldering drops etc...).



**Figure 1.**

**Caution:** Never bond the sensor to a painted surface. Always scrape the paint off beforehand.

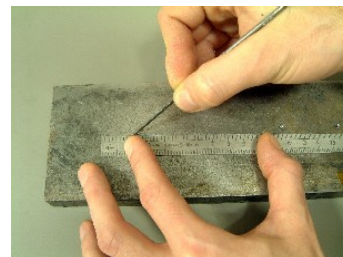
- Rub abrasive paper on the mounting surface, as well as on the sensor mounting plates (fig. 1).
- Clean the mounting surface as well as the sensor mounting plates with a cloth soaked with solvent (acetone). (fig. 2). Rub always in the same direction.



**Figure 2.**

**Caution:** If mounting plates have already been used, remove remaining glue tracks, then degrease.

- Draw position marks for the sensor on the mounting surface using a scribe. (fig. 3).
- Clean this surface with a cloth soaked with solvent (acetone) Rub always in the same direction.
- Let dry for some minutes.

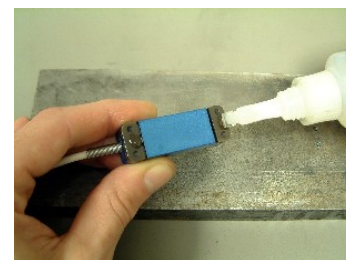


**Figure 3.**

## II. SENSOR BONDING:

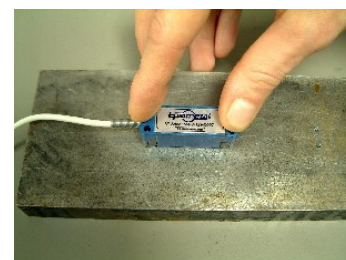
### 1. CYANOACRYLAT GLUE.:

- Put a drop of glue on each mounting plate of the Sensor (fig 4).
- Apply immediately the sensor on the mounting surface, paying close attention to align it along the marks drawn beforehand. Maintain a slight pressure on the sensor ends for one minute or two (fig 5).
- Let the glue polymerize during 10 minutes, before applying a strain on the sensor.



**Figure 4.**

**NB:** Cyanoacrylat glue is recommended for a short term use, its good behaviour is limited in time.



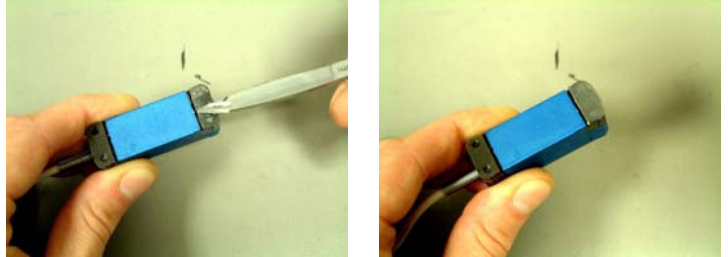
**Figure 5.**

## **2. EPOXY BI-COMPONENTS GLUE:**

- Drop the adhesive and hardener in a cupel, and then mix them using a spatula, for small quantities (fig 6). Preparing larger quantities, it is recommended to use the manual gun with a mixing tube.
- Spread out à fine layer of adhesive on each mounting plate. (fig 7)
- Apply the sensor on the mounting surface, paying close attention to align it along the marks drawn beforehand.
- Hold in place the sensor with adhesive tape on each end while the glue is polymerizing. (fig 8)
- Let the glue polymerize during 3 hours at ambient temperature (20°) or 30 minutes at 80°c before removing the tape. Wait for 24 hours before performing a measurement.



**Figure 6.**



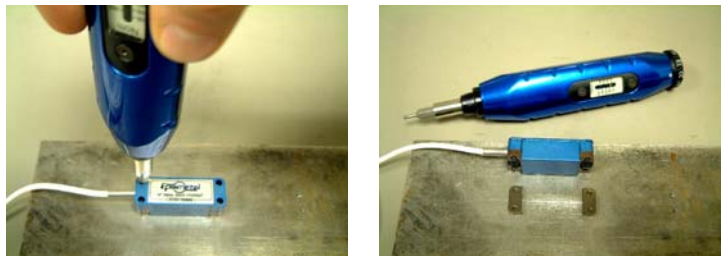
**Figure 7.**



**Figure 8.**

## **III. REMOVING THE SENSOR:**

- Using a torque wrench, or a 2mm hexagonal wrench, release the 2 screws at one end of the sensor. Then the screws at the other end .( fig 9)
- Remove the sensor. Both mounting plates remain bonded on the mounting surface.
- To release the plates, position a small chisel against the side of the plate, then with a hammer, apply a small but firm stroke on the plate.



**Figure 9.**

***TIP:*** Holding in place the mounting plates with a small piece of adhesive tape can avoid losing them while releasing. (fig 10)



**Figure 10.**

**Caution :** Use only wrench in good condition; a damaged screw prevents from removing the sensor, and can result in a severe damage to the sensor. Change screws as soon as the first sign of tear and wear is noticed.

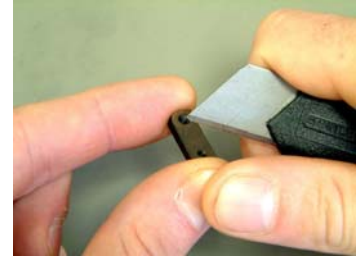


# RE-USING THE SENSOR

## I. MOUNTING THE PLATES ON A SENSOR AND RE-USING IT:

- If mounting plates have already been used, remove the glue marks using a cutter and abrasive paper. (fig 11-12).
- Set up the 1<sup>st</sup> plate with a slight tightening of each screw, using the hexagonal end of the torque wrench or a 2mm hexagonal spanner. (fig 13)
- Then proceed the same way with the 2<sup>nd</sup> one.
- Align the marks on sensor and plates.
- Apply the sensor on a plane surface or in the positioning gauge.
- Using a torque wrench, tighten progressively and successively each screw of a mounting plate, up to 1Nm torque. (fig 14)

Then proceed the same way with the 2<sup>nd</sup> one.

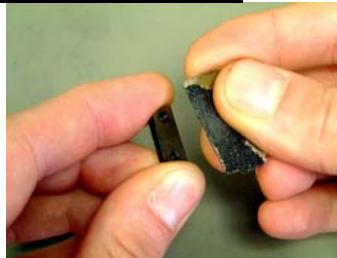


**Figure 11.**

- Rub the sensor on abrasive paper, **upon a flat surface to avoid irregular wear.**
- Clean the mounting surface as well as the sensor mounting plates with a cloth soaked with solvent (acetone). (fig. 2).

**The sensor is ready for use**

**CAUTION:** *tightening at a wrong torque may result in an inaccurate measurement and 0 shift (if < 1 Nm) or may damage the screws (> 1 Nm)*



**Figure 12.**



**Figure 13.**



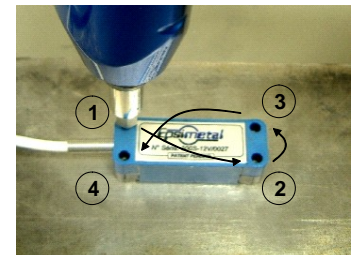
**Figure 14.**

## II. RE-USING A SENSOR ON BONDED PLATES:

Set up the sensor on his plates with a slight tightening of each screw. Tighten successively each screw in X. (fig 15).

Then tighten successively in the same way each screw at 1 Nm, using the torque wrench.

The same procedure may be used to fasten directly the sensor in M2.5 tapped holes. In this case, intercalate a 1.5 mm thick brace between the sensor and the mounting surface.



**Figure 15.**

# USING DIGITAL ADJUSTMENT:

(Only available for high level output sensors)

Thanks to the EPSILOG interface, it is possible to adjust some parameters like offset value, scale value (gain), set points values (option), or to save or load new data files.

You need: a PC with RS 232 serial port, an interface box, an "EPSILOG" software.

Using digital adjustment is not essential for an ordinary use. But It allows on site adjustments when necessary.

## 1. AVAILABLE FUNCTIONS :

- a. Port com.  
Communication port selection.
- b. Save EEPROM.  
Save sensor adjustment parameters in .txt file.
- c. Offset adjustment.  
Automatic adjustment of the offset value.
- d. Gain adjustment.  
Automatic adjustment of the output scale value.
- e. Alarm level adjustment (soon available).
- f. Calibration.  
Two points calibration of the output scale/any input measurand (Strain, stress, Strength, torque)
- g. Display.  
Display the current output value.
- h. Load EEPROM.  
Loading a new adjustment file, or re-loading the original adjustment file.
- i. Data acquisition.  
Display signal curve and save data in a file. (Higher sampling rate= 100 ms, depending on the serial port and the PC).
- j. Save last data.  
Save last acquisition data in a file.

**NB :** The menus may show some differences, depending on the activated optional functions.

## 2. EPSILOG program set up.

- a. Minimum requirements
  - o 850 MHz processor
  - o 64 Mo RAM
  - o Windows 98 or NT2000 or XP.
- b. Set up
  - o Insert EPSILOG CD ROM in driver.
  - o Open CD ROM directory (double click)
  - o Open **EPSILOG** directory (double click)
  - o Double click on "**install.exe**" or "**setup.exe**"
  - o Follow displayed instructions.
- c. Running

- o Start menu> Programs> **EPSILOG** directory
- o Double click on "**Epsilog.exe**".

### 3. CONNECTING THE INTERFACE BOX

#### d. General information

The connection between the two green connectors is a “by-pass”. So you can insert the box in the sensor connection. You also can connect the sensor on one side and a power supply on the other side (also a voltmeter). The power supply feeds both sensor and interface. You can use the unpluggable connecting block or the socket, or the mating socket adaptation. The SUB D9 socket is connected to a RS232 adapter which allows bi-directional data transfer.

#### e. Connecting the box.

- Connect one side to the sensor (fig 16). Please, refer to colour code on the last page.
- Connect the other side to the panel, or to the power supply.
- Connect SUB D9 socket to a serial port of your PC.
- Start “EPSILOG” program.

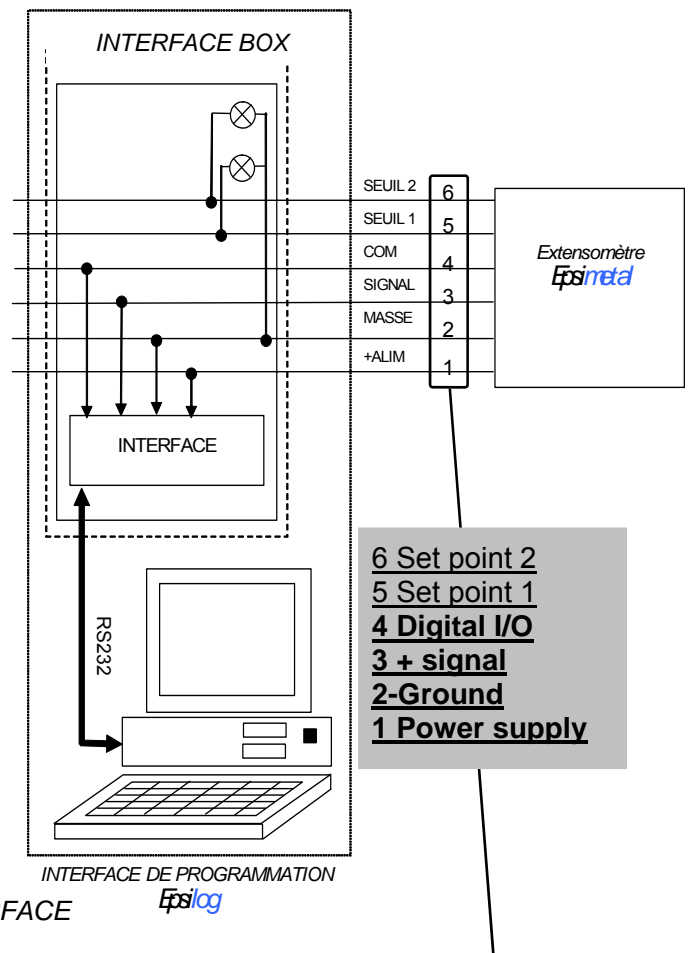
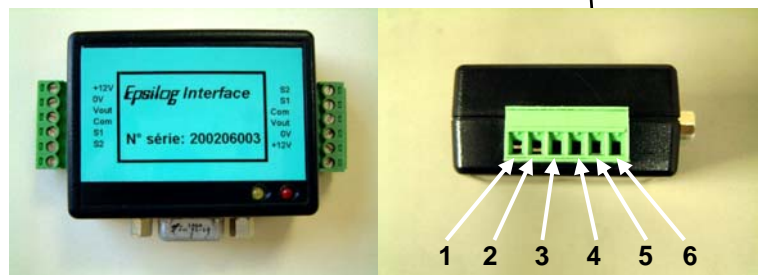


Fig 16



### 2. USING PARAMETER ADJUSTMENT.

You can select a menu line by clicking on it or by clicking arrow up or down at the bottom of the EPSILOG window. Then click “OK” to activate the function. Clicking on OK starts a function or gets back to the menu when it's over. Clicking on “Exit” gets back to the previous menu or quits the program when in the main menu.

#### a. Port com.

If your PC is equipped with several serial ports, or if an error message occurs, you have to select the good one.

- Click on “port com”, then on OK.
- Select the port on which you are connected, using arrows up or down then clicking “OK”.
- When “port com open” is displayed, click “OK”.

#### b. Save EEPROM

#### **Be careful:**

**When you are about to change any parameter, always save the EEPROM content beforehand.**

- Select “save EEPROM”, then OK.
- The program reads automatically parameters in the strain sensor memory.
- Choose filename and directory when asked.

Once this operation is done, you can modify the sensor memory.

### ***Be careful:***

*Filename is your only reference for file identification. Choose it carefully; it must contain at least:*

- *Sensor serial number*
- *Calibration identification*
- *date*

#### c. Offset adjustment

- Select “offset adjustment”, then OK.
- Enter final value (Volt) when asked.
- Offset adjustment is done automatically.
- The new value is displayed when the operation is over.
- Select OK to get back to the menu.

**Caution:** *be sure that the sensor is at its 0 position and that no strain occurs while operating adjustment.*

#### d. Gain adjustment

*This operation is a modification of the internal electrical gain of the sensor, without calibration.*

- Select “gain adjustment”, then OK.
- Enter the current output scale (volt) value corresponding to a given input span ( $\mu$ strain, Strength....) when asked, then “OK”.
- Enter the output span you want to get (volt) corresponding to the same input span, then OK.

**Caution:** *after this operation you must re-adjust offset when the sensor is back to its 0 position.*

#### e. Calibration

*This operation is a two point calibration of the output scale of the sensor. The sensor must be properly installed and ready to use. It needs application of two different loadings on the feature you want to calibrate (one of them could be 0).*

- Select “calibration”, then “OK”.
- When “enter minimum tension value” is displayed, enter the output value (volt) you want for the lower value of your input span, using the arrows up or down, and then “OK”.
- When “enter maximum tension value” is displayed, enter the output value (volt) you want for the upper value of your input span, using the arrows up or down, and then “OK”.
- When “apply the 1<sup>st</sup> load” is displayed, apply the load corresponding to your 1<sup>st</sup> calibration point. (This load can be 0)
- Then enter the % of full scale corresponding to this load and then “OK”.
- When “apply the 2nd load” is displayed, apply the load corresponding to your 2nd calibration point. (This load must be > 1<sup>st</sup> load).
- Then enter the % of full scale corresponding to this load and then “OK”.
- Remove the load; the strain sensor is adjusted.

#### **Tip:**

*You can improve the results, if you let the sensor work once or twice between max load and 0 before performing a calibration.*

#### **Tip:**

*Do not enter “0V” as lower output value. This is a saturation value.*



**For example :**

- Suppose you want to calibrate a strain sensor bonded on a beam, 5V at sensor's output corresponding to 10 kg input span, with an offset value of 0.5V.
- You have a 8 kg reference load.
- "enter minimum tension value": **enter "0.5"**
- "enter maximum tension value": **enter "5.5"**
- "apply 1<sup>st</sup> load": **let the beam free of load.**
- "...": **enter "0%", and then OK.**
- "apply 2<sup>nd</sup> load": **Apply the 8 kg load on the beam.**
- "...": **enter "80%", and then "OK".**
- Remove the load.
- Your sensor must display 0.500 V.

f. Set points adjustment

(Soon available)

g. Loading file in EEPROM

**Be careful:**

**When you are about to change any parameter, always save the EEPROM content**

You can get back to a previous adjustment.

- Select "loading file in EEPROM", then OK.
- Select the file you want to load in the strain sensor memory.
- Select OK.

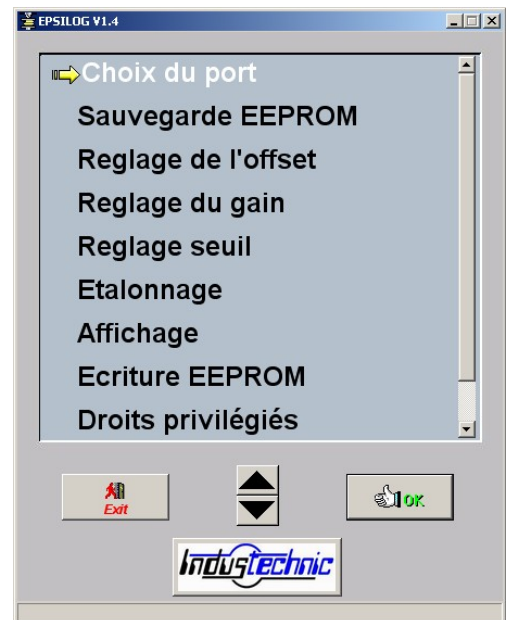
h. Data acquisition.

You can display sensor signal as a curve. You can also save data in a text file or in an excel file.

- Select "Data acquisition".
- Select "Sampling"
- If necessary, enter the sampling period (not less than 125)
- Select OK.
- Select "File type"
- Tick the file extension you want.
- Select OK.
- When ready, select "Go"
- To stop acquisition, click on "OK"
- When asked, click on "OK" if you want to save data.
- To quit data acquisition program, select "exit"

i. Save last acquisition.

You can save the last data, if it was not done before quitting acquisition.



**Remarks :**

In every menu, « **Exit** » returns to the preceding menu. « **OK** » carries out the subroutine, or confirm the next step, or stops it when it is running. In the main menu,, « **Exit** » quits the main routine.

# DATA SHEET: HIGH LEVEL OUTPUT SENSORS

The items with built-in strain gages conditioning system are only concerned

These data are not contractual and are only indicative.

## I. TECHNICAL DATA :

### 1. INPUT :

Power input (\*)

Mini : +9V

Maxi : +28V( !)

Insulation resistance : 2M $\Omega$

! Caution: only for new versions manufactured after October 31<sup>st</sup>, 2007.

The former versions with "12" in designation are limited to 18V

The former versions with "24" in designation are limited between 15 and 24V

### 2. OUTPUT (STANDARD VERSION) :

Strain range: +/-500  $\mu\text{m/m}$

Mechanical overload: +/- 1000  $\mu\text{m/m}$

Resolution : 0.1  $\mu\text{m/m}$

Output span 5 V (floating) for 1000  $\mu\text{m/m}$

Free offset value: 3 V

Max electrical overload: 7 V

Min electrical overload: -0.070 V

Linearity : <0.8% EM

Hysteresis : <0.2% EM

With 4-20 mA converter:

Output span 10 mA (floating) for 1000  $\mu\text{m/m}$

Free offset value: 12 mA

Max electrical overload: 23 mA

Min electrical overload: 2.55 mA

### 3. OPERATIONAL CONDITIONS :

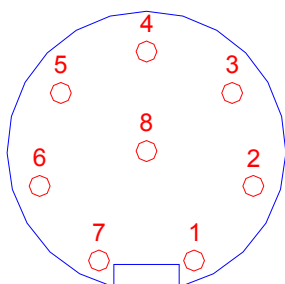
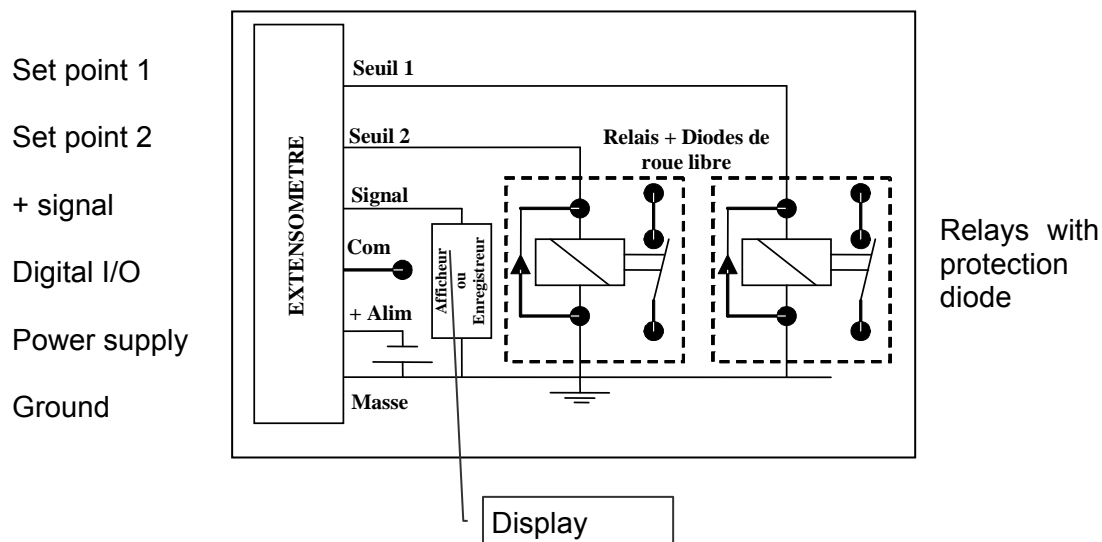
Operational temperature : -40°C to +85°C

Temperature compensation: -10°C to +50°C

Compensated material: steel.

## II. WIRING (VOLTAGE OUTPUT) :

Item exemple : 450475,450477, 450472, 450478.



**Front view of connector pins position**  
**(Réf numbers with connector only)**

Connector pos.	Wiring	Colour / Cable model		
		Red, black, white, green, (3)	Red, black, white, green, yellow, blue (4)	Brown, green, yellow, white, pink, grey.
1	<b>+ Power supply</b>	Red	Red	<b>Brown</b>
2	<b>- Common</b>	Black	Black	<b>Green</b>
3	<b>+ Signal</b>	White	White	<b>Yellow</b>
4	Digital I/O	Green (1)	Green (1)	White (1)
5	Set point 1 (2)		Blue (1)	Pink (1)
6	Set point 2 (2)		Yellow (1)	Grey (1)

(1) Insulate wire end when it is not connected

(2) Only on demand

(3) Only for ref 450488

(4) Only for obsolete versions still in service



## 2. OUTPUT :

Strain range:	+/-500 $\mu\text{m/m}$
Mechanical overload:	+/- 1000 $\mu\text{m/m}$
Output span :	4 to 6 mV/V for 1000 $\mu\text{m/m}$
Linearity :	<0.8% EM
Hysteresis :	<0.5% EM
Offset value :	$0 \pm 1.5 \text{ mV/V}$

The offset value is only indicative. This value is depending upon the bonding conditions and the quality of surfaces. There is no temperature compensation on the mV versions, and the scale is not adjusted.

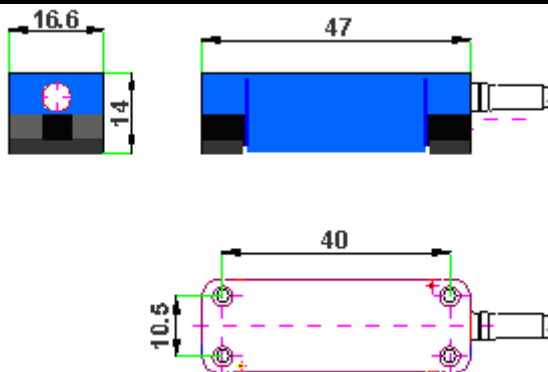
## II. WIRING :

Wiring (mV output) (item 450491)	Type 1 cable	Type 2 cable
<b>+ bridge excitation</b>	<b>Brown</b>	<b>Red</b>
<b>- bridge excitation</b>	<b>Green</b>	<b>Black</b>
<b>+ signal</b>	<b>Yellow</b>	<b>White</b>
<b>- signal</b>	<b>White</b>	<b>Green or Blue</b>

## CONVENTION

Consider a positive signal in extension and a negative signal in compression

## SIZE DRAWING



Photos non contractuelles. SCAIME se réserve le droit d'apporter toute modification sans préavis.